

BACnet Protocol Implementation Conformance Statement

Date: Vendor Name: Product Name: Product Model Number: Software Version: BACnet Protocol Revision:	16-06-2023 FlowCon International FlowCon FH Actuator with BACnet FH-BUS 2.04 1.22				
Product Description: Electrical modulating actuator with BUS	communication (BACnet or Modbus) for PICV: FlowCon Green.3.				
BACnet Standardized Device Profile □ BACnet Operator Workstation (B-OW □ BACnet Building Controller (B-BC) □ BACnet Advanced Application Control □ BACnet Application Specific Controlle □ BACnet Smart Sensor (B-SS) □ BACnet Smart Actuator (B-SA)	oller (B-AAC)				
List all BACnet Interoperability Build Data Sharing BIBBs: DS-RP-B DS-RPM-B DS-WP-B DS-WPM-B DS-COV-B	ing Blocks Supported (Annex K): Data Sharing - Read Property - B Data Sharing - Read Property Multiple - B Data Sharing - Write Property - B Data Sharing - Write Property Multiple - B Data Sharing - Change Of Value - B				
Device Management BIBBs: DM-DDB-B DM-DOB-B DM-DCC-B DM-TS-B DM-RD-B DM-R-B	-B Device Management - Dynamic Device Binding - B -B Device Management - Dynamic Object Binding - B -B Device Management - Device Communication Control - B -B Device Management - Time Synchronization - B				
Segmentation Capability: This device	does not support segmentation.				
Data Link Layer Options: □ BACnet IP, (Annex J) □ BACnet IP, (Annex J), Foreign Device □ ISO 8802-3, Ethernet (Clause 7) □ ASTM 878.1, 2.5 Mb. ARCNET (Clause 8) □ ASTM 878.1, RS-485 ARCNET (Clause 8) baud rate(s): ☑ MS/TP master (Clause 9), baud rate(s): 9600, 19200, 38400, 57600 and 115200 □ MS/TP slave (Clause 9), baud rate(s): 9600, 19200, 38400, 57600 and 115200 □ Point-To-Point, EIA 232 (Clause 10), baud rate(s): max. EIA 232 □ Point-To-Point, modem, (Clause 10), baud rate(s): max. modem □ LonTalk, (Clause 11), medium: □ Other:					



Device Address Binding: Is static device binding supported? (This is currently necessary certain other devices.) ☐ Yes ☑ No	for two-wa	ay communication with MS/TP slaves and
Networking Options: This device has no special networking operations. ☐ Router, Clause 6 - List all routing configurations. ☐ Annex H, BACnet Tunneling Router over IP. ☐ BACnet Broadcast Management Device (BBMD). ☐ Does the BBMD support registrations by Foreign Devices? ☐ Does the BBMD support network address translation?	ptions. ☐ Yes ☐ Yes	□ No □ No
Character Sets Supported: Indicating support for multiple character sets does not imply that ☑ UTF-8 ☐ IBM™/Microsoft™ DBCS ☐ ISO 8859-1 ☐ ISO 10646 (UCS-2) ☐ ISO 10646 (UCS-4) ☐ JIS X 0208 ☐ ISO 10646 (UTF-8)	it they can	all be supported simultaneously.



List of Objects

Analog Input (AI):

Name	Description	R/W	Present-Value Options
Serial number, software version	Actuator firmware serial number and software version	R	Software version x.xx (e.g. 2.03).
Analog input P1	Measured input value at port 1	R	Unit depending on selected sensor type (°C, °K or %).
Analog input P2	Measured input value at port 2	R	Unit depending on selected sensor type (°C, °K or %).
Target position	Target position for the actuator piston	R	0 to 15. Unit in millimeters.
Actual position	Actual position of the actuator piston	R	0 to 15. Unit in millimeters.
Actual value control signal	Actual flow rate in percent og max. flow setting	R	0 to 100. Unit is %.
Actual volume flow rate	Actual flow rate calculated based on valve parameters	R	0 to 65535. Unit is I/hours.
Differential temperature	Actual water ΔT calculated based on measured supply and return temperatures	R	-200 to +200. Unit is °K.
Flush timer, actual value	Timer: Remaining time until start of flushing procedure	R	0 to 4320. Unit in hours until last hour then in minutes.
Valve blocking protection timer, actual value	Timer: Remaining time until start of valve blocking protection procedure	R	0 to 4320. Unit in hours.
Operating hours	Life statistics: Total operating time of the actuator	R	0 to 1193046. Unit in hours.
Distance counter	Life statistics: Total travel distance of the actuator	R	0 to 4294967295. Unit is millimeters.
Overall stroke	Total stroke (distance between upper and lower end postion)	R	0 to 15. Unit in millimeters.
Actual volume flow rate limitation	Max. flow depending on selected valve	R	50 to 50000. Unit is I/hours. Automatic and depending on selection in MSV.8.
Actual value of thermal power	Current calculated value of thermal power goint through the valve. Calculated value only valid for PICVs	R	0 to 65535. Unit is kW.
Energy, running day	Current day from 00:00. Calculated value only valid for PICVs	R	0 to 65535. Unit is kWh.
Energy, 24 hours back	Current time and 24 hours back. Calculated value only valid for PICVs	R	0 to 65535. Unit is kWh.
	Serial number, software version Analog input P1 Analog input P2 Target position Actual position Actual value control signal Actual volume flow rate Differential temperature Flush timer, actual value Valve blocking protection timer, actual value Operating hours Distance counter Overall stroke Actual volume flow rate limitation Actual value of thermal power Energy, running day	Serial number, software version Actuator firmware serial number and software version Analog input P1 Measured input value at port 1 Analog input P2 Measured input value at port 2 Target position Target position for the actuator piston Actual position Actual position of the actuator piston Actual value control signal Actual flow rate in percent og max. flow setting Actual volume flow rate Actual flow rate calculated based on valve parameters Differential temperature Actual water ΔT calculated based on measured supply and return temperatures Flush timer, actual value Timer:	Serial number, software version Actuator firmware serial number and software version R Analog input P1 Measured input value at port 1 R Analog input P2 Measured input value at port 2 R Target position Target position for the actuator piston R Actual position Actual position of the actuator piston R Actual value control signal Actual flow rate in percent og max. flow setting R Actual value control signal Actual flow rate in percent og max. flow setting R Actual value value parameters Actual flow rate calculated based on valve parameters R Differential temperature Actual flow rate calculated based on measured supply and return temperatures R Flush timer, actual value Timer:

Analog Output (AO):

#	Name	Description	R/W	Present-Value Options
1	Analog output P2	Output value of port 2, for configuration of sensor / output type port 2. ~0 to 10V output	R/W	0 to 100. Unit is %.

Analog Value (AV):

#	Name	Description	R/W	Present-Value Options
1	External control signal	External Volume flow rate set point (actuating signal)	R/W	0 to 100 (-10 to 110). Unit is %.
2	Minimum control signal	Set minimum control signal limit	R/W	0 to 100. Unit is %.
3	Maximum control signal	Set maximum control signal limit	R/W	0 to 100. Unit is %.
4	Supply temperature	Supply water temperature	R/(W)	-50 to +150. Unit is °C. Write-protected when source is Port 1 or Port 2.
5	Return temperature	Return water temperature	R/(W)	-50 to +150. Unit is °C. Write-protected when source is Port 1 or Port 2.
6	Correction value P1	Correction factor for port 1	R/W	-5 to +5.
7	Correction value P2	Correction factor for port 2	R/W	-5 to +5.



Analog Value (AV), continued:

#	Name	Description	R/W	Present-Value Options
8	Emergency position	Failsafe position in case of BUS communication failure or invalid control function	R/W	0 to 100. Unit in %. 30
10	Valve blocking protection timer	Set valve block protection timer, i.e. the time between two valve block protection procedures	R/W	0 to 4320. Unit is hours. 0=not active.
11	Hydraulic balancing value for heating	Range between minimum and maximum flow rate of selected valve in heating mode	R/W	0 to 65535. Unit is I/hours.
12	Hydraulic balancing value for cooling	Range between minimum and maximum flow rate of selected valve in cooling mode	R/W	0 to 65535. Unit is I/hours.
14	Medium energy constant	Energy constant for used hydraulic medium	R/W	180 to 18000. Unit is J/(kg * °K). 4183= water.
15	Хр	Xp - proportional gain contant of PI controller	R/W	2 to 6000.
16	Tn	Tn - time constant of PI controller	R/W	0 to 720. Unit is seconds.
17	Room temperature actual value	Actual room temperature	R/(W)	-50 to +150. Unit is °C. Write-protected when source is Port 1 or Port 2.
18	Room temperature setpoint	Room temperature setpoint	R/W	0 to 50. Unit is °C.
19	Thermal power setpoint	Thermal power setpoint. Positive values for heating and cooling	R/W	0 to 5000. Unit is kW.
20	Return temperature setpoint	Return water temperature setpoint	R/W	0 to 120. Unit is °C.
22	Maximum thermal power limiting value	Set max. value for thermal power. Positive values for heating and cooling	R/W	0 to 5000. Unit is kW. 0= not active.
23	Return temperature limiting value	Return water temperature limiting value.	R/W	0 to 120. Unit is °C. 0= not active.
28	MAC address	MAC address	R/(W)	1 to 127. Writeable when actuator DIP switches are set to 63.
29	Close when adjusting range	Upper and lower end position range where actuator remains in end position	R/W	0 to 5. Unit is %.
30	Kvs value of the selected valve			NO FUNCTION. Value is set by valve selection in MSV.8.
31	Xp thermal power limitation	Gain constant for power limitation	R/W	2 to 6000.
32	Xp return temperature limitation	Gain constant for return water temperature limitation	R/W	2 to 6000.
35	Flush timer	Set flush timer, i.e. the time between two flushing procedures	R/W	0 to 4320. Unit in hours. 0= not active.

Binary Input (BI):

#	Name	Description	R/W	Present-Value Options
1	Binary input P1	Input in port 1	R	0= Off 1= On
2	Binary input P2	Input in port 2	R	0= Off 1= On
3	Actuator is busy	Operating status: Actuator mode	R	0= Normal operation (no message shown) 1= Actuator is not available for control signal
4	Actuator in malfunction	Operating error status: Hardware fault	R	0= Normal operation (no message shown) 1= Hardware fault (Port 1 or Port 2 range exceeded or similar malfunction)



Binary Input (BI), continued:

#	Name	Description	R/W	Present-Value Options
5	Error during valve adaption	Operating error status: Valve calibration error	R	0= Normal operation (no message shown) 1= Error during valve adaption
6	Error: valve blocking	Operating error status: Valve blocking error	R	0= Normal operation (no message shown) 1= Error, valve is blocked
7	Warning: leak detected	Operating error status: Leak detection warning	R	0= No warning 1= Leak detected (ΔT above 8 °K when valve is closed for more than 6 hours)
8	Limit function active	External control signal overwritten due to exceeded limit value	R	

Binary Value (BV):

#	Name	Description	R/W	Present-Value Options
1	P1 inversion (binary input)	Port 1 direct or inverse operating mode (binary input)	R/W	<u>0= Direct</u> 1= Inverted Works with MSV.2= 2.
2	P2 inversion (binary input)	Port 2 direct or inverse operating mode (binary input)	R/W	<u>0= Direct</u> 1= Inverted Works with MSV.3= 2.
3	P2 inversion (analog output)	Port 2 direct or inverse operating mode (analog output)	R/W	<u>0= Direct</u> 1= Inverted Works with MSV.3= 9.
4	Inversion of the valve actuating direction	Actuator direction	R/W	0= Normally closed 1= Normally open

Multi-State Input (MSI):

#	Name	Description	R/W	Present-Value Options
1	Status of HVAC mode (Changeover)		R	1= Shut-off 2= Heating 3= Cooling

Multi-State Value (MSV):

#	Name	Description	R/W	Present-Value Options
1	Service command	Service command	R/W	1= Normal operation mode 2= Calibration mode 3= Test run mode 4= Synchronize valve 5= Reset error messages 6= Reset BUS 7= Reset to factory settings
2	Sensor type P1	Port 1 sensor type	R/W	1= OFF 2= Binary input 3= 0-10V input 4= KP10 5= Ni1000-DIN 6= Ni1000-LG 7= PT1000 8= Potentiometer 10°K 9= Potentiometer 10°K +/-3°K 10= Potentiometer 10°K +/-5°K
3	Sensor/Output type P2	Port 2 sensor type / output	R/W	1= OFF 2= Binary input 3= 0-10V input 4= KP10 5= Ni1000-DIN 6= Ni1000-LG 7= PT1000 8= Potentiometer 10°K 9= 0-10V output (set in AO.1) 10= 0-10V Y position feedback (set in Al.6) 11= Changeover signal for 6-way valve (set in MSV.9)
4	Operating mode	Operating mode	R/W	1= External control signal (set in AV.1) 2= Open ~ 100% 3= Closed ~ 0% 4= Minimum position (set in AV.2) 5= Res. 6= Maximum position (set in AV.3) 7= Room temperature (set in AV.17 and AV.18) 8= Control by thermal power (set in Al.16 and AV.19) 9= Return water temperature (set in AV.5 and AV.20)



Multi-State Value (MSV), continued:

#	Name	Description	R/W	Present-Value Options
5	Source of supply and return temperature	Water temperature source, supply and return	R/W	1= BUS (set in AV.4 and AV.5) 2= Port 1 supply, Port 2 return 3= Port 2 supply, Port 1 return 4= Port 1 supply, BUS return 5= Port 2 supply, BUS return 6= BUS supply, Port 1 return 7= BUS supply, Port 2 return
6	Communication failure mode	Action in case of communication failure	R/W	1= fail in place 2= close (after 120 seconds) 3= open (after 120 seconds) 4= fail position, set in AV.8 (after 120 seconds)
7	Select RS485 baud rate	RS-485 baud rate	R/W	1= Default (38400) 2= 9600
8	Select valve type	Select valve type and control characteristics	R/W	1= Linear (generic) 2= Green.3 3= EQ% (generic) 4= Unser-Valve
9	Choose HVAC mode (Changeover)	HVAC mode (changeover mode)	R/W	1= Shut-off 2= Heating 3= Cooling 4= Automatic based on supply temperature (MSV.3≠11)
10	Select source for room temperature	Room temperature source	R/W	1= BUS (set AV.17) 2= Port 1 3= Port 2
11	LED mode	LED indication	R/W	1= OFF 2= ON without BUS 3= ON with BUS
12	Actuating speed	Actuator speed	R/W	<u>1= 22 s/mm</u> 2= 28 s/mm 3= 16 s/mm
13	Actuator Control Curve	Actuator Control Curve (input and feedback)	R/W	0= Linear 1= Equal%

Network Port (NP):

#	<u> </u>	Name	Description	R/W	Present-Value Options
1		Network port MS/TP			